

ΜΑΘΗΜΑ

ΦΥΣΙΚΗ ΠΡΟΣΑΝΑΤΟΛΙΣΜΟΥ

ΛΥΣΕΙΣ

ΤΑΞΗ

Γ' ΛΥΚΕΙΟΥ

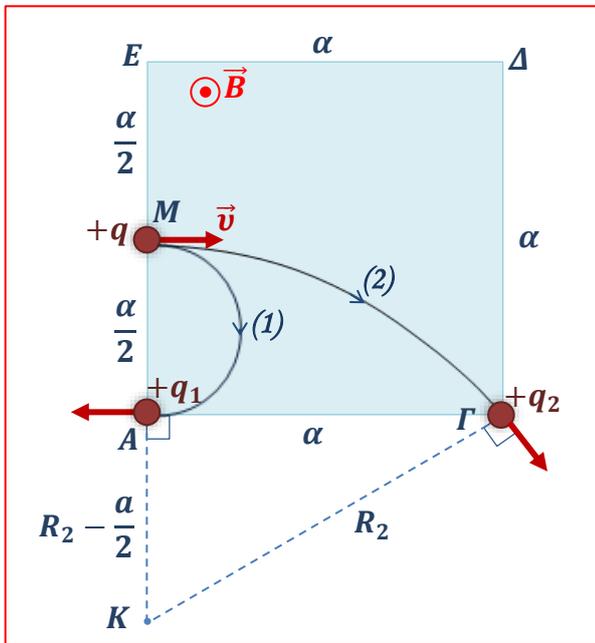
ΕΞΕΤΑΣΤΕΑ ΥΛΗ ΚΡΟΥΣΕΙΣ, ΣΤΕΡΕΟ, ΤΑΛΑΝΤΩΣΕΙΣ, ΚΥΜΑΤΑ, ΜΑΓΝΗΤΙΚΟ ΠΕΔΙΟ, Η/Μ ΕΠΑΓΩΓΗ

ΘΕΜΑ Α

- A.1. δ A.2. γ A.3. β A.4. δ A.5. α, Λ, β, Λ, γ, Σ, δ, Σ, ε, Σ

ΘΕΜΑ Β

B.1. α



Σωματίδιο (1): $R_1 = \frac{\alpha}{4}$ (1)

Σωματίδιο (2): Τρίγωνο \widehat{KAG} $R_2^2 = \alpha^2 + \left(R_2 - \frac{\alpha}{2}\right)^2 \Rightarrow$

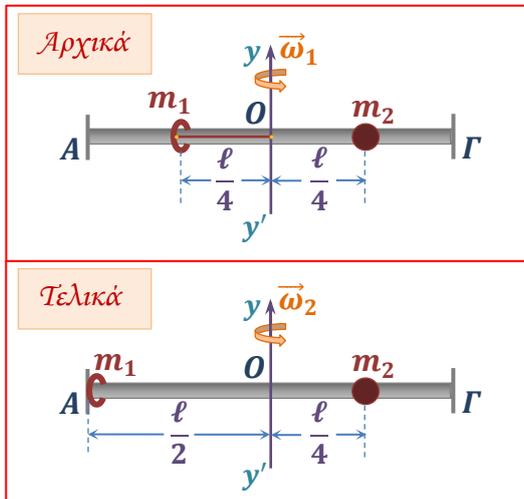
$\Rightarrow R_2^2 = \alpha^2 + R_2^2 - R_2\alpha + \frac{\alpha^2}{4} \Rightarrow R_2\alpha = \frac{5\alpha^2}{4} \Rightarrow$

$\Rightarrow R_2 = \frac{5\alpha}{4}$ (2)

$\frac{(1)}{(2)} \rightarrow \frac{R_1}{R_2} = \frac{1}{5} \Rightarrow R_2 = 5R_1 \Rightarrow \frac{m_2 \cdot v}{B \cdot q_2} = 5 \frac{m_1 \cdot v}{B \cdot q_1} \Rightarrow$

$\Rightarrow \frac{m_2 \cdot v}{B \cdot q_2} = 5 \frac{m_1 \cdot v}{B \cdot 5q_2} \Rightarrow \boxed{m_2 = m_1}$

B.2. β



A.Δ.Σ.: $L_{ολ}^{(αρχ)} = L_{ολ}^{(τελ)} \Rightarrow$

$\Rightarrow (m_1 + m_2)\omega_1 \left(\frac{\ell}{4}\right)^2 = m_1\omega_2 \left(\frac{\ell}{2}\right)^2 + m_2\omega_2 \left(\frac{\ell}{4}\right)^2 \Rightarrow$

$\Rightarrow m_1\omega_1 \frac{\ell^2}{16} + m_2\omega_1 \frac{\ell^2}{16} = m_1\omega_2 \frac{\ell^2}{4} + m_2\omega_2 \frac{\ell^2}{16} \Rightarrow$

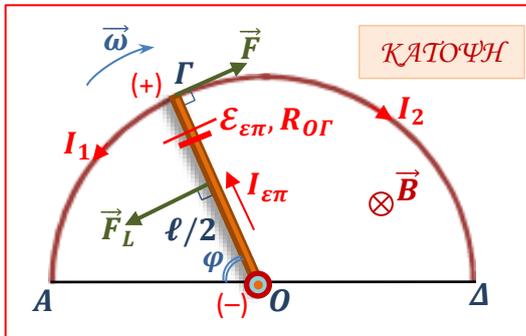
$\xrightarrow{(\omega_1=3\omega_2)} \frac{3}{16}m_1 + \frac{3}{16}m_2 = \frac{1}{4}m_1 + \frac{1}{16}m_2 \Rightarrow$

$$\Rightarrow \frac{2}{16} m_2 = \frac{1}{16} m_1 \Rightarrow m_1 = 2m_2 \quad (1)$$

$$\frac{K_{o\lambda}^{(\alpha\rho\chi)}}{K_{o\lambda}^{(\tau\epsilon\lambda)}} = \frac{\frac{1}{2} m_1 \omega_1^2 \left(\frac{\ell}{4}\right)^2 + \frac{1}{2} m_2 \omega_1^2 \left(\frac{\ell}{4}\right)^2}{\frac{1}{2} m_1 \omega_2^2 \left(\frac{\ell}{2}\right)^2 + \frac{1}{2} m_2 \omega_2^2 \left(\frac{\ell}{4}\right)^2} \xrightarrow{(\omega_1=3\omega_2)} \frac{K_{o\lambda}^{(\alpha\rho\chi)}}{K_{o\lambda}^{(\tau\epsilon\lambda)}} = \frac{\frac{1}{2} m_1 9\omega_2^2 \frac{\ell^2}{16} + \frac{1}{2} m_2 9\omega_2^2 \frac{\ell^2}{16}}{\frac{1}{2} m_1 \omega_2^2 \frac{\ell^2}{4} + \frac{1}{2} m_2 \omega_2^2 \frac{\ell^2}{16}} \Rightarrow$$

$$\stackrel{(1)}{\Rightarrow} \frac{K_{o\lambda}^{(\alpha\rho\chi)}}{K_{o\lambda}^{(\tau\epsilon\lambda)}} = \frac{9m_2 + \frac{9}{2}m_2}{4m_2 + \frac{1}{2}m_2} \Rightarrow \frac{K_{o\lambda}^{(\alpha\rho\chi)}}{K_{o\lambda}^{(\tau\epsilon\lambda)}} = \frac{\frac{27}{2}m_2}{\frac{9}{2}m_2} \Rightarrow \boxed{\frac{K_{o\lambda}^{(\alpha\rho\chi)}}{K_{o\lambda}^{(\tau\epsilon\lambda)}} = 3}$$

B.3. γ



$$\left. \begin{aligned} R_{A\Gamma} &= \rho \frac{(A\Gamma)}{s} \\ R_{\Gamma\Delta} &= \rho \frac{(\Gamma\Delta)}{s} \end{aligned} \right\} \begin{aligned} (\div) \Rightarrow \frac{R_{A\Gamma}}{R_{\Gamma\Delta}} &= \frac{(A\Gamma)}{(\Gamma\Delta)} \Rightarrow \frac{R_{A\Gamma}}{R_{\Gamma\Delta}} = \frac{\frac{\pi}{3}\ell}{\frac{2\pi}{3}\ell} \Rightarrow \\ \Rightarrow \frac{R_{A\Gamma}}{R_{\Gamma\Delta}} &= \frac{1}{2} \Rightarrow R_{\Gamma\Delta} = 2R_{A\Gamma} \quad (1) \end{aligned}$$

Επίσης, ισχύει ότι: $R_{A\Gamma} + R_{\Gamma\Delta} = 3R \stackrel{(1)}{\Rightarrow} R_{A\Gamma} + 2R_{A\Gamma} = 3R \Rightarrow 3R_{A\Gamma} = 3R \Rightarrow R_{A\Gamma} = R \quad (2)$

Επομένως (1) $\stackrel{(2)}{\rightarrow} R_{\Gamma\Delta} = 2R \quad (3)$

$$R_{o\lambda} = \frac{R_{A\Gamma} \cdot R_{\Gamma\Delta}}{R_{A\Gamma} + R_{\Gamma\Delta}} + R_{o\Gamma} \stackrel{(2),(3)}{\Rightarrow} R_{o\lambda} = \frac{R \cdot 2R}{R + 2R} + \frac{R}{3} \Rightarrow R_{o\lambda} = \frac{2R}{3} + \frac{R}{3} \Rightarrow R_{o\lambda} = R \quad (4)$$

$$I_{\epsilon\pi} = \frac{\epsilon_{\epsilon\pi}}{R_{o\lambda}} \stackrel{(4)}{\Rightarrow} I_{\epsilon\pi} = \frac{\frac{1}{2} B \omega \ell^2}{R} \quad (5)$$

$$\omega = \text{σταθ.} \rightarrow \Sigma \tau^{(o)} = 0 \Rightarrow \tau_F^{(o)} + \tau_{F_L}^{(o)} = 0 \Rightarrow F\ell - F_L \frac{\ell}{2} = 0 \Rightarrow F = \frac{F_L}{2} \Rightarrow$$

$$\Rightarrow F = \frac{B I_{\epsilon\pi} \ell}{2} \stackrel{(5)}{\Rightarrow} \boxed{F = \frac{B^2 \omega \ell^3}{4R}}$$

ΘΕΜΑ Γ

Γ.1.

$$T = \frac{1}{f} \Rightarrow T = \frac{1}{2,5} \text{ s} \Rightarrow T = 0,4 \text{ s}$$

$$t_1 = t_M + \frac{T}{4} \Rightarrow t_1 = \frac{x_M}{v_\delta} + \frac{T}{4} \Rightarrow 0,5 = \frac{0,4}{v_\delta} + 0,1 \Rightarrow \frac{0,4}{v_\delta} = 0,4 \Rightarrow v_\delta = 1 \text{ m/s}$$

$$v_\delta = \lambda f \Rightarrow \lambda = \frac{v_\delta}{f} \Rightarrow \lambda = \frac{1}{2,5} \text{ m} \Rightarrow \boxed{\lambda = 0,4 \text{ m}}$$

Γ.2.

Επειδή $v_\delta > 0$ και $\varphi_0 = 0$: $\varphi = 2\pi \left(\frac{t}{T} - \frac{x}{\lambda} \right) \Rightarrow \left\{ \begin{array}{l} \varphi_M = 2\pi \left(\frac{t}{T} - \frac{x_M}{\lambda} \right) \\ \varphi_N = 2\pi \left(\frac{t}{T} - \frac{x_N}{\lambda} \right) \end{array} \right\} \Rightarrow$

$$\Rightarrow \left\{ \begin{array}{l} \varphi_M = 2\pi \frac{t}{T} - 2\pi \frac{x_M}{\lambda} \\ \varphi_N = 2\pi \frac{t}{T} - 2\pi \frac{x_N}{\lambda} \end{array} \right\} \stackrel{(-)}{\Rightarrow} \varphi_M - \varphi_N = -2\pi \frac{x_M}{\lambda} + 2\pi \frac{x_N}{\lambda} \Rightarrow \Delta\varphi_{M,N} = \frac{2\pi}{\lambda} (x_N - x_M) \Rightarrow$$

$$\Rightarrow \frac{3\pi}{4} = \frac{2\pi}{0,4} (x_N - 0,4) \Rightarrow x_N - 0,4 = \frac{3}{20} \Rightarrow x_N = (0,4 + 0,15) \text{ m} \Rightarrow \boxed{x_N = 0,55 \text{ m}}$$

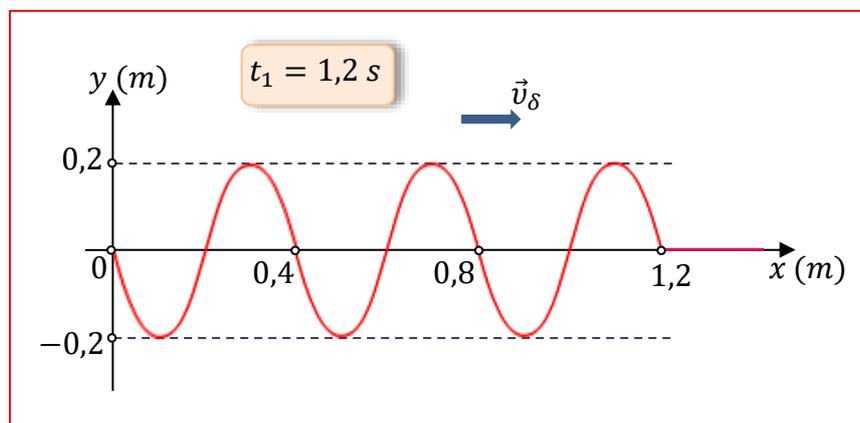
Γ.3.

Τη στιγμή $t = t_2 = 1,2 \text{ s}$:

$$y = A \cdot \eta\mu 2\pi \left(\frac{t}{T} - \frac{x}{\lambda} \right) \Rightarrow y_2 = 0,2 \cdot \eta\mu 2\pi \left(\frac{1,2}{0,4} - \frac{x}{0,4} \right) \Rightarrow y_2 = 0,2 \cdot \eta\mu(6\pi - 5\pi x) \text{ (S.I.)}$$

$$x_2 = v_\delta \cdot t_2 \Rightarrow x_2 = 1,2 \text{ m}$$

$$\left. \begin{array}{l} x_2 = 1,2 \text{ m} \\ \lambda = 0,4 \text{ m} \end{array} \right\} \stackrel{(\div)}{\Rightarrow} \frac{x_2}{\lambda} = 3 \Rightarrow x_2 = 3\lambda$$



Γ.4.

α' τρόπος:

$$y_M = A \cdot \eta \mu \varphi_M \Rightarrow \frac{A}{2} = A \cdot \eta \mu \varphi_M \Rightarrow \eta \mu \varphi_M = \frac{1}{2}$$

Ισχύει ότι: $\eta \mu^2 \varphi_M + \sigma \nu \nu^2 \varphi_M = 1 \Rightarrow \sigma \nu \nu \varphi_M = \pm \sqrt{1 - \eta \mu^2 \varphi_M} \Rightarrow$

$$\Rightarrow |\sigma \nu \nu \varphi_M| = \sqrt{1 - \frac{1}{4}} \Rightarrow |\sigma \nu \nu \varphi_M| = \sqrt{\frac{3}{4}} \Rightarrow |\sigma \nu \nu \varphi_M| = \frac{\sqrt{3}}{2}$$

Άρα $v_M = \omega A \cdot \sigma \nu \nu \varphi_M \Rightarrow |v_M| = 2\pi f A \cdot |\sigma \nu \nu \varphi_M| \Rightarrow |v_M| = 2\pi f A \cdot |\sigma \nu \nu \varphi_M| \Rightarrow$

$$\Rightarrow |v_M| = 5\pi \cdot 0,2 \cdot \frac{\sqrt{3}}{2} \text{ m/s} \Rightarrow \boxed{|v_M| = \frac{\sqrt{3}\pi}{2} \text{ m/s}}$$

β' τρόπος:

Α.Δ.Ε.Τ.: $\frac{1}{2}DA^2 = \frac{1}{2}mv_M^2 + \frac{1}{2}Dy_M^2 \Rightarrow v_M^2 = \frac{D}{m}(A^2 - y_M^2) \xrightarrow{(D=m\omega^2)}$

$$\Rightarrow v_M^2 = \omega^2(A^2 - y_M^2) \Rightarrow v_M^2 = 4\pi^2 f^2(A^2 - y_M^2) \Rightarrow v_M^2 = 4\pi^2 \cdot 6,25 \cdot (0,2^2 - 0,1^2) \text{ m}^2/\text{s}^2 \Rightarrow$$

$$\Rightarrow v_M^2 = 25\pi^2 \cdot 0,03 \text{ m}^2/\text{s}^2 \Rightarrow v_M^2 = 0,75\pi^2 \text{ m}^2/\text{s}^2 \Rightarrow v_M^2 = \frac{3}{4}\pi^2 \text{ m}^2/\text{s}^2 \Rightarrow$$

$$\Rightarrow |v_M| = \frac{\sqrt{3}\pi}{2} \text{ m/s}$$

Γ.5.

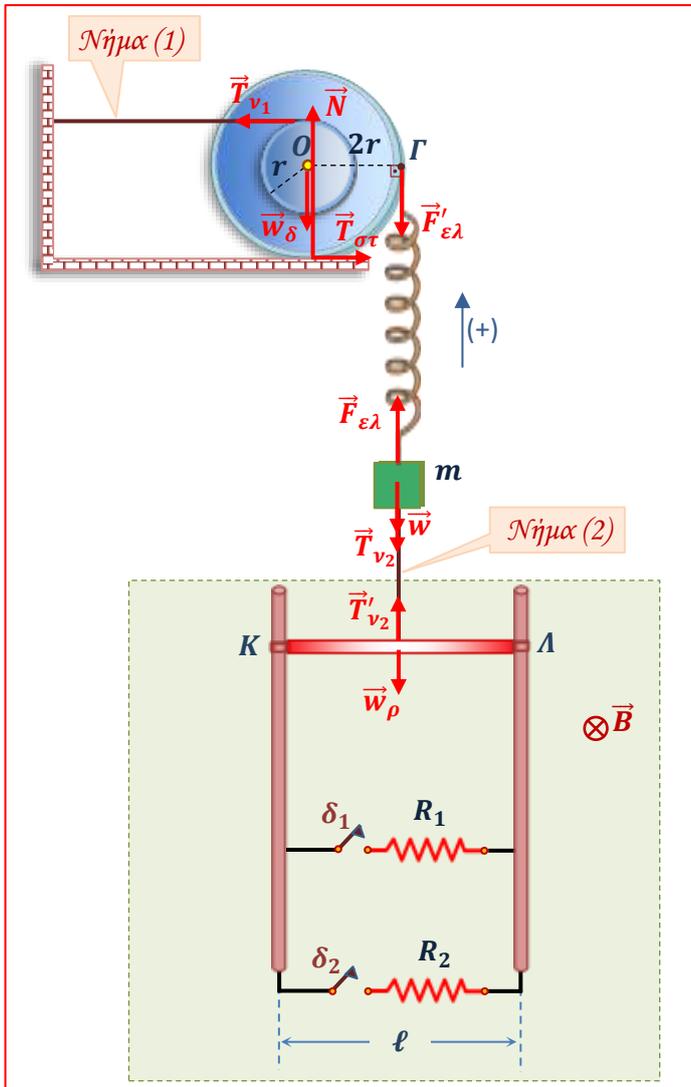
Ίδιο μέσο διάδοσης: $v'_\delta = v_\delta \Rightarrow \lambda' f' = \lambda f \Rightarrow \lambda' = \frac{\lambda f}{f'} \Rightarrow \lambda' = \frac{\lambda f}{2f} \Rightarrow \lambda' = 0,2 \text{ m}$

Άρα $\varphi'_M - \varphi'_N = \left(2\pi \frac{t}{T'} - 2\pi \frac{x_M}{\lambda'}\right) - \left(2\pi \frac{t}{T'} - 2\pi \frac{x_N}{\lambda'}\right) \Rightarrow \Delta\varphi'_{M,N} = \frac{2\pi}{\lambda'}(x_N - x_M) \Rightarrow$

$$\Rightarrow \Delta\varphi'_{M,N} = \frac{2\pi}{0,2}(0,55 - 0,4) \text{ rad} \Rightarrow \boxed{\Delta\varphi'_{M,N} = \frac{3\pi}{2} \text{ rad}}$$

ΘΕΜΑ Δ

Δ.1.



Ισοροπία ράβδου ΚΛ:

$$\Sigma F_y = 0 \Rightarrow T'_{v_2} = w_\rho \Rightarrow T'_{v_2} = M_\rho g \Rightarrow T'_{v_2} = 10 \text{ N}$$

Αβαρές νήμα (2): $T_{v_2} = T'_{v_2} \Rightarrow T_{v_2} = 10 \text{ N}$

Ισοροπία σώματος μάζας m, μέσω του νήματος (2):

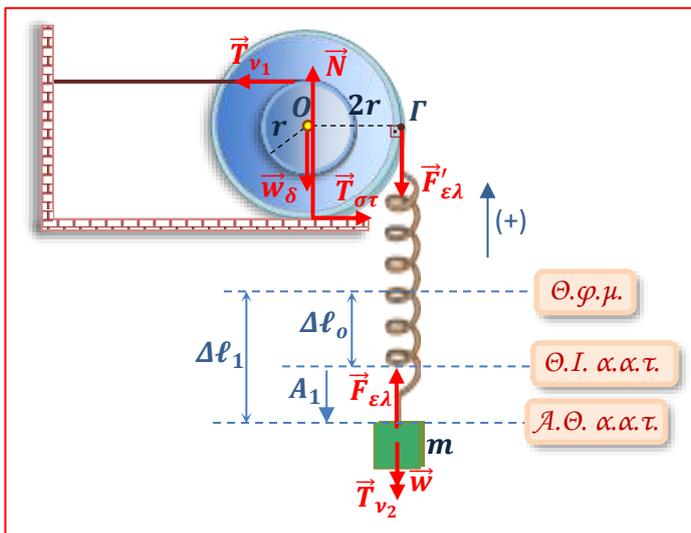
$$\Sigma F_y = 0 \Rightarrow F_{\varepsilon\lambda} = T_{v_2} + w \Rightarrow F_{\varepsilon\lambda} = T_{v_2} + mg \Rightarrow F_{\varepsilon\lambda} = (10 + 20) \text{ N} \Rightarrow F_{\varepsilon\lambda} = 30 \text{ N}$$

Αβαρές ελατήριο: $F'_{\varepsilon\lambda} = F_{\varepsilon\lambda} \Rightarrow F'_{\varepsilon\lambda} = 30 \text{ N}$

Ισοροπία δίσκου:

$$\left. \begin{aligned} \Sigma \tau^{(O)} = 0 &\Rightarrow T_{v_1} \cdot r + T_{\sigma\tau} \cdot 2r = F'_{\varepsilon\lambda} \cdot 2r \\ \text{και } \Sigma F_x = 0 &\Rightarrow T_{v_1} = T_{\sigma\tau} \end{aligned} \right\} \Rightarrow T_{v_1} \cdot r + T_{v_1} \cdot 2r = F'_{\varepsilon\lambda} \cdot 2r \Rightarrow T_{v_1} \cdot 3r = F'_{\varepsilon\lambda} \cdot 2r \Rightarrow T_{v_1} = \frac{2}{3} F'_{\varepsilon\lambda} \Rightarrow T_{v_1} = \left(\frac{2}{3} \cdot 30\right) \text{ N} \Rightarrow \boxed{T_{v_1} = 20 \text{ N}}$$

Δ.2.



Η θέση ισοροπίας του σώματος μάζας m , μέσω του νήματος (2), ταυτίζεται με την κάτω ακραία θέση ταλάντωσής του, μετά το κόψιμο του νήματος. Από το ερώτημα Δ.1., στη θέση αυτή έχουμε ότι:

$$F_{\varepsilon\lambda} = 30 \text{ N} \Rightarrow k\Delta\ell_1 = 30 \Rightarrow \Delta\ell_1 = 0,3 \text{ m}$$

Θ.Ι. α.α.τ. του σώματος μάζας m:

$$\Sigma F_y = 0 \Rightarrow F_{\varepsilon\lambda_0} = w \Rightarrow k\Delta\ell_0 = mg \Rightarrow \Delta\ell_0 = 0,2 \text{ m}$$

$$\text{Άρα } A_1 = \Delta\ell_1 - \Delta\ell_0 \Rightarrow A_1 = 0,1 \text{ m}$$

Με την ίδια λογική, βρίσκουμε ότι $A_{max} = \Delta\ell_{max} - \Delta\ell_o \Rightarrow A_{max} = \frac{F_{ελ_{max}}}{k} - 0,2$ (1)

Δίνεται ότι $A_{max} = 2A_1 \Rightarrow A_{max} = 0,2 \text{ m}$ (2)

Επομένως (1) $\xrightarrow{(2)}$ $0,2 = \frac{F_{ελ_{max}}}{k} - 0,2 \Rightarrow \frac{F_{ελ_{max}}}{k} = 0,4 \Rightarrow F_{ελ_{max}} = 40 \text{ N}$

Αβαρές ελατήριο: $F'_{ελ_{max}} = F_{ελ_{max}} \Rightarrow F'_{ελ_{max}} = 40 \text{ N}$

Ισορροπία περιστροφής δίσκου ως προς το κέντρο του:

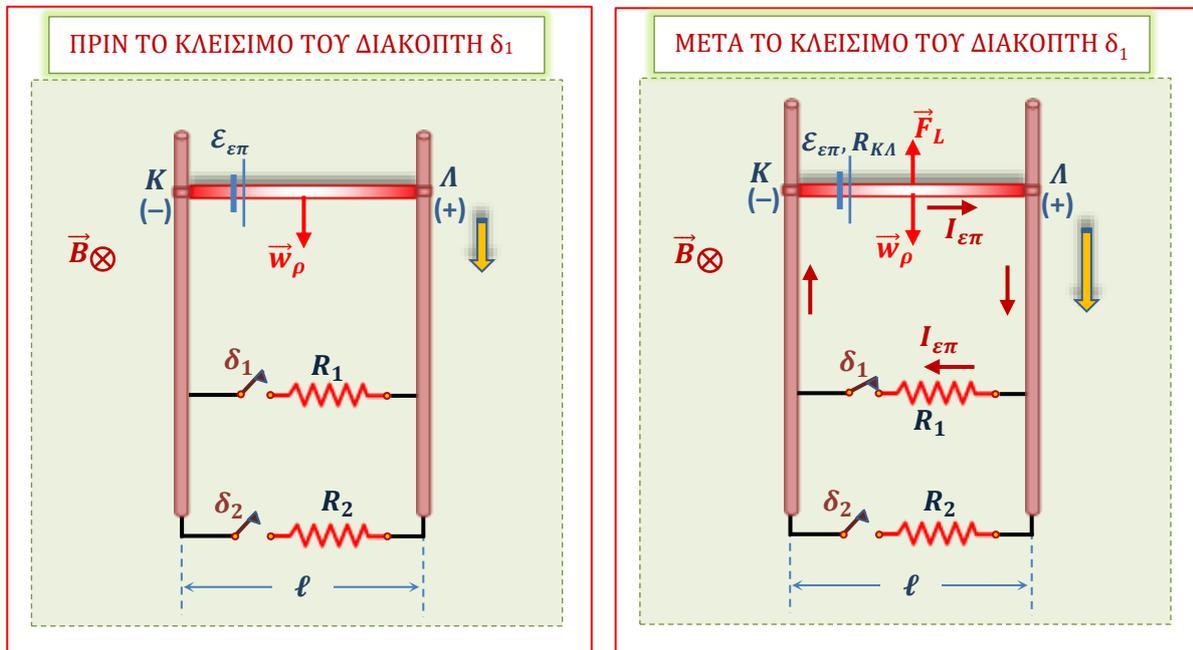
$$\begin{aligned} \Sigma\tau^{(o)} = 0 &\Rightarrow T_{v_1} \cdot r + T_{\sigma\tau} \cdot 2r = F'_{ελ} \cdot 2r \xrightarrow{(T_{v_1}=T_{\sigma\tau})} T_{\sigma\tau} \cdot 3r = F'_{ελ} \cdot 2r \Rightarrow \\ &\Rightarrow T_{\sigma\tau_{max}} \cdot 3r = F'_{ελ_{max}} \cdot 2r \Rightarrow T_{\sigma\tau_{max}} = \frac{2}{3} F'_{ελ_{max}} \Rightarrow T_{\sigma\tau_{max}} = \frac{80}{3} \text{ N} \Rightarrow \mu_{ορ} \cdot N = \frac{80}{3} \text{ N} \end{aligned} \quad (3)$$

Ισορροπία μεταφοράς δίσκου στον άξονα y'y:

$$\Sigma F_y = 0 \Rightarrow N = w_{\delta} + F'_{ελ_{max}} \Rightarrow N = M_{\delta}g + F'_{ελ_{max}} \Rightarrow N = 80 \text{ N} \quad (4)$$

Επομένως (3) $\xrightarrow{(4)}$ $\boxed{\mu_{ορ} = \frac{1}{3}}$

Δ.3.



ΠΡΙΝ το κλείσιμο του διακόπτη δ_1 : $\Sigma F_y = w_{\rho} \Rightarrow M_{\rho} \cdot \alpha = M_{\rho} \cdot g \Rightarrow \alpha = 10 \text{ m/s}^2$

Τη στιγμή $t_1 = 1 \text{ s}$: $v_1 = \alpha \cdot t_1 \Rightarrow v_1 = 10 \text{ m/s}$

και $V_{\Lambda K_1}^{(\pi\rho\nu)} = \mathcal{E}_{\varepsilon\pi_1} \Rightarrow V_{\Lambda K_1}^{(\pi\rho\nu)} = Bv_1\ell \Rightarrow V_{\Lambda K_1}^{(\pi\rho\nu)} = 10 \text{ V}$

ΜΕΤΑ το κλείσιμο του διακόπτη δ_1 , τη στιγμή t_1 :

$$I_{\varepsilon\pi_1} = \frac{\varepsilon_{\varepsilon\pi_1}}{R_{o\lambda}} \Rightarrow I_{\varepsilon\pi_1} = \frac{Bv_1\ell}{R_1 + R_{K\Lambda}} \Rightarrow I_{\varepsilon\pi_1} = \frac{10}{3 + 2} \text{ A} \Rightarrow I_{\varepsilon\pi_1} = 2 \text{ A}$$

$$V_{\Lambda K_1}^{(\mu\epsilon\tau\acute{\alpha})} = \varepsilon_{\varepsilon\pi_1} - I_{\varepsilon\pi_1} \cdot R_{K\Lambda} \Rightarrow V_{\Lambda K_1}^{(\mu\epsilon\tau\acute{\alpha})} = Bv_1\ell - I_{\varepsilon\pi_1} \cdot R_{K\Lambda} \Rightarrow$$

$$\Rightarrow V_{\Lambda K_1}^{(\mu\epsilon\tau\acute{\alpha})} = (10 - 2 \cdot 2) \text{ V} \Rightarrow V_{\Lambda K_1}^{(\mu\epsilon\tau\acute{\alpha})} = 6 \text{ V}$$

$$\text{Άρα } \pi(\%) = \frac{V_{\Lambda K_1}^{(\mu\epsilon\tau\acute{\alpha})} - V_{\Lambda K_1}^{(\pi\rho\nu\nu)}}{V_{\Lambda K_1}^{(\pi\rho\nu\nu)}} \cdot 100(\%) \Rightarrow \pi(\%) = \frac{6 - 10}{10} \cdot 100(\%) \Rightarrow \boxed{\pi(\%) = -40\%}$$

Δ.4.

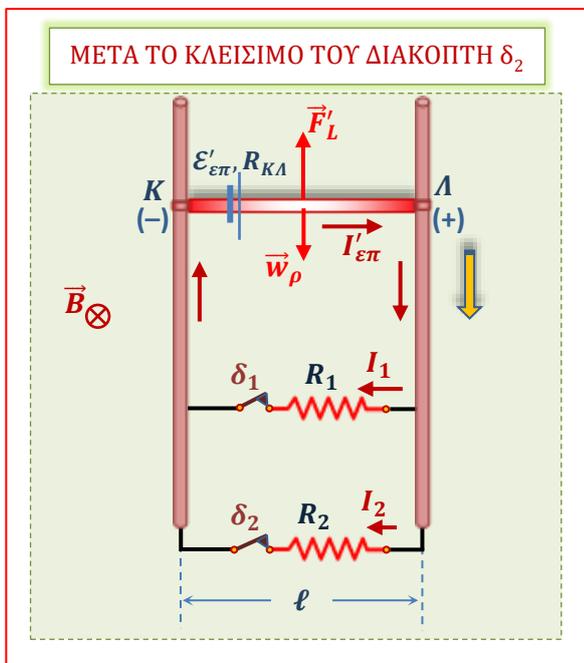
Τη στιγμή t_2 , ακριβώς πριν το κλείσιμο του διακόπτη δ_2 , ισχύει ότι:

$$\frac{dp}{dt} = 0 \Rightarrow \Sigma F_y = 0 \Rightarrow F_L = w_\rho \Rightarrow BI_{\varepsilon\pi}\ell = M_\rho g \Rightarrow B \frac{\varepsilon_{\varepsilon\pi}}{R_1 + R_{K\Lambda}} \ell = M_\rho g \Rightarrow$$

$$\Rightarrow B \frac{Bv\ell}{R_1 + R_{K\Lambda}} \ell = M_\rho g \xrightarrow{(v=v_{o\rho})} \frac{B^2\ell^2}{R_1 + R_{K\Lambda}} v_{o\rho} = M_\rho g \Rightarrow v_{o\rho} = \frac{M_\rho g (R_1 + R_{K\Lambda})}{B^2\ell^2} \Rightarrow$$

$$\Rightarrow v_{o\rho} = \frac{10 \cdot (3 + 2)}{2^2 \cdot 0,5^2} \text{ m/s} \Rightarrow v_{o\rho} = 50 \text{ m/s}$$

Τη στιγμή t_2 , αμέσως μετά το κλείσιμο του διακόπτη δ_2 , ισχύει ότι:



$$R'_{o\lambda} = \frac{R_1 \cdot R_2}{R_1 + R_2} + R_{K\Lambda} \Rightarrow R'_{o\lambda} = \left(\frac{3 \cdot 6}{3 + 6} + 2 \right) \Omega \Rightarrow$$

$$\Rightarrow R'_{o\lambda} = 4 \Omega$$

$$F'_L = BI'_{\varepsilon\pi}\ell = B \frac{\varepsilon'_{\varepsilon\pi}}{R'_{o\lambda}} \ell = B \frac{Bv\ell}{R'_{o\lambda}} \ell = \frac{B^2\ell^2}{R'_{o\lambda}} v \xrightarrow{(v=v_{o\rho})}$$

$$\Rightarrow F'_L = \frac{2^2 \cdot 0,5^2}{4} \cdot 50 \text{ N} \Rightarrow F'_L = 12,5 \text{ N}$$

$$\Sigma F'_y = w_\rho - F'_L = M_\rho g - F'_L \Rightarrow \Sigma F'_y = -2,5 \text{ N}$$

$$\text{Άρα } \frac{dK}{dt} = \Sigma F'_y \cdot v \xrightarrow{(v=v_{o\rho})} \frac{dK}{dt} = -2,5 \cdot 50 \text{ J/s} \Rightarrow$$

$$\Rightarrow \boxed{\frac{dK}{dt} = -125 \text{ J/s}}$$

Δ.5.

Από τη στιγμή t_2 και μετά, η ράβδος εκτελεί *επιβραδυνόμενη κίνηση με φθίνουσα επιβράδυνση*, αφού:

$$\Sigma F'_y < 0 \Rightarrow |v| \downarrow \text{ και } |\alpha'| = \frac{|w_\rho - F'_L|}{M_\rho} \xrightarrow{(F'_L > w_\rho)} |\alpha'| = \frac{F'_L - w_\rho}{M_\rho} = \frac{B^2 \ell^2}{M_\rho R'_{o\lambda}} v - g \xrightarrow{(|v| \downarrow)} |\alpha'| \downarrow$$

Όταν $v = 48 \text{ m/s}$, θα έχουμε:

$$I'_{\varepsilon\pi} = \frac{Bv\ell}{R'_{o\lambda}} \Rightarrow I'_{\varepsilon\pi} = \frac{48}{4} \text{ A} \Rightarrow I'_{\varepsilon\pi} = 12 \text{ A}$$

$$\begin{cases} I'_{\varepsilon\pi} = I_1 + I_2 \\ I_1 R_1 = I_2 R_2 \end{cases} \Rightarrow \begin{cases} 12 = I_1 + I_2 \\ 3I_1 = 6I_2 \end{cases} \Rightarrow \begin{cases} 12 = I_1 + I_2 \\ I_1 = 2I_2 \end{cases} \Rightarrow 12 = 3I_2 \Rightarrow I_2 = 4 \text{ A}$$

Επομένως, η θερμική ισχύς που καταναλώνει η αντίσταση R_2 ισούται με:

$$P_{R_2} = I_2^2 \cdot R_2 \Rightarrow P_{R_2} = 4^2 \cdot 6 \text{ W} \Rightarrow \boxed{P_{R_2} = 96 \text{ W}}$$